



Scheduling

Motivation and definition of terms

- References for this chapter
- [Stallings2011] Stallings, M. Operating Systems, second edition, Prentice-Hall, 2006
 - [ADKOM2012] Ada Reference Manual - Language Formal Syntax and Semantics, SORMC 60522/19.1.0

Scheduling

Motivation and definition of terms

- Purpose of scheduling
- Two scenarios for scheduling algorithms:
 - 1. Ordering, resource assignments (CPU time, network access, ...),
 - in live, on-line application or scheduling algorithms,
 - 2. Predicting system behaviours under anticipated loads,
 - as simulated, or in application of scheduling algorithms,
- Predictions are used:
- of complete time to confirm the feasibility of the system, or to predict resource needs, ...
 - of run time to permit advance of new requests or for load-balancing, ...

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Scheduling

Motivation and definition of terms

Criteria

Process / user perspective:	minimize the...	maximize the...
Waiting time	minima / maxima / average / variance	minima / maxima / average
Response time	minima / maxima / average / variance	CPU busy time
Turnaround time	minima / maxima / average / variance	
System perspective:	minimize deviation from given...	
	value / minima / maxima	
	value / minima / maxima / deadlines	

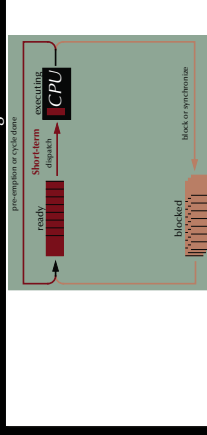
Predictability criteria:

- minimize deviation from given... value / minima / maxima
- value / minima / maxima / deadlines

Scheduling

Definition of terms

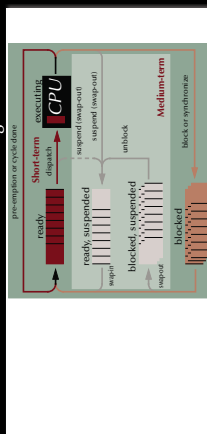
Time scales of scheduling



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Definition of terms

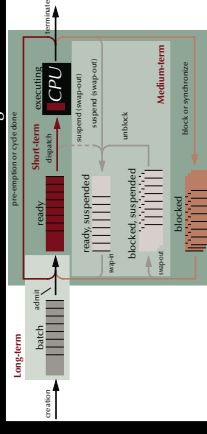
Time scales of scheduling



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Definition of terms

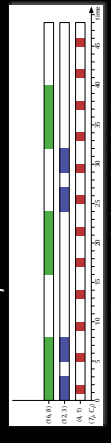
Time scales of scheduling



Scheduling

Performance scheduling

Requested resource times

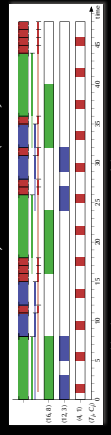


Tasks have an average time between interruptions of and a constant computation time of

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Performance scheduling

First come, first served (FCFS)

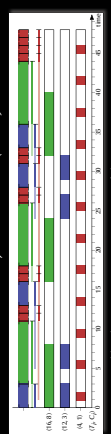


As tasks apply concurrently for resources, the actual sequence of arrival is non-deterministic, as there even a deterministic scheduling algorithm like FCFS can lead to different outcomes.

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Performance scheduling

First come, first served (FCFS)



Waiting time: 0.31, average: 0.4, Turnaround time: 1.02, average: 0.4

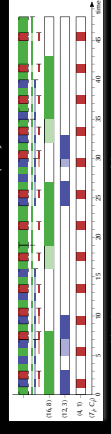
In this example, waiting times vary between 1.4 and 2.0, the average turn and times vary between 0.9 and 0.4

Shortest possible, maximal turnaround time!

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Performance scheduling

Round Robin (RR)



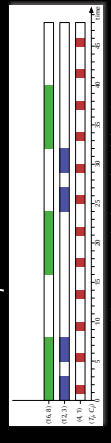
Waiting time: 0.5, average: 1.2 - Turnaround time: 2.0, average: 0.8

- Optimized for swift initial responses,
- Stretches out long tasks,
- Bounded maximal waiting time (dependent only on the number of tasks)

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Performance scheduling

Feedback with 2ⁱ pre-emption intervals

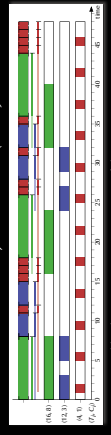


- Implement multiple hierarchical ready-queues,
- Fetch processes from the highest filled ready queue,
- Dispatch more CPU time for those priorities (i.e. units),
- Processes on lower ranks may suffer starvation,
- New and short tasks will be preferred.

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Performance scheduling

First come, first served (FCFS)



Waiting time: 0.5, average: 1.5 - Turnaround time: 1.21, average: 0.7

Optimized for swift initial responses,

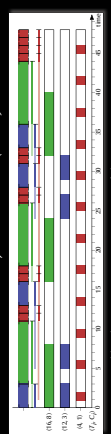
Priorities short tasks and long tasks can suffer starvation,

Very short initial response times and good average turnaround times.

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Performance scheduling

Feedback with 2ⁱ pre-emption intervals - overlapping



Waiting time: 0.3, average: 0.9 - Turnaround time: 1.45, average: 0.77

Optimized for swift initial responses,

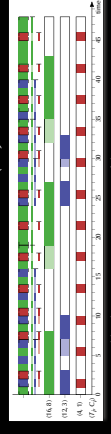
Priorities short tasks and long tasks can suffer starvation,

Long tasks are delayed until all queues run empty!

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Performance scheduling

Shortest job first



Waiting time: 0.1, average: 0.7 - Turnaround time: 1.1, average: 0.3

Optimized for good average performance with minimal task switches,

Priorities short tasks but all tasks will be handled,

Good choice if computation times are known and task switches are expensive!

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Performance scheduling

Shortest job first

Waiting time: 0.10, average: 3.4 – Turnaround time: 1.14, average: 6.0

- Can be sensitive to non-deterministic arrival sequences.

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Performance scheduling

Highest Response Ratio $\frac{W_i + C_i}{C_i}$ First (HRRF)

Waiting time: 0.9, average: 4.1 – Turnaround time: 2.13, average: 6.6

- Blend between Shortest-Job-First and First-Come-First-Served.
- Prefers short tasks but long tasks gain preference over time.
- More task switches and worse averages than SJF but better upper bounds!

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Performance scheduling

Shortest Remaining Time First (SRTF)

Waiting time: 0.6, average: 0.7 – Turnaround time: 1.21, average: 4.4

- Optimized for good averages.
- Prefers short tasks and long tasks can suffer starvation.
- Better averages than Feedback scheduling but with longer absolute waiting times!

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Performance scheduling

Comparison (in order of appearance)

- FCFS
- RR
- SJF
- SRTF
- HRRF
- FB

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Comparison by shortest maximal waiting

- Providing upper bounds to waiting times
- Swift response systems

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Performance scheduling

Comparison by shortest average waiting

- Providing short average waiting times
- Very swift response in most cases

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Scheduling

Performance scheduling

Comparison by shortest maximal turnaround

- Providing upper bounds to turnaround times
- No tasks are left behind

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Performance scheduling

Comparison by shortest average turnaround

- Providing good average performance
- High throughput systems

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Performance scheduling

Comparison overview

	Selection	Pre-emption	Waiting	Turnaround	Preferred jobs	Starvation possible?
Methods without any knowledge about the processes						
FCFS	$\max(W_i)$	no	long	long average, & short maximum	equal	no
RR	equal share	yes	bound	good average & large maximum	short	no
FB	priority queues	yes	very short	short average & long maximum	short	no
Methods employing computation time C_i and elapsed time E_i						
SJF	$\min(C_i)$	no	medium	medium	short	yes
HRRF	$\max(\frac{W_i + C_i}{C_i})$	no	controllable compromise	controllable compromise	controllable	no
SRTF	$\min(C_i - E_i)$	yes	very short	wide variance	short	yes

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Scheduling

Predictable scheduling

Towards predictable scheduling ...

Task requirements (Quality of service):

- Guarantee data flow levels
- Guarantee reaction times
- Guarantee deadlines
- Guarantee delivery times
- Provide bounds for the variations in results

Examples:

- Streaming media broadcasts, playing HD videos, live mixing audio/video, ...
- Reacting to users, Reacting to alarm situations, ...
- Delivering a signal to the physical world at the required time, ...

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Scheduling

Predictable scheduling

Temporal scopes

Common attributes:

- Minimal & maximal delay after creation
- Maximal elapsed time
- Maximal execution time
- Absolute deadline

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Scheduling

Predictable scheduling

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Predictable scheduling

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Scheduling

Predictable scheduling

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Scheduling

Predictable scheduling

Common temporal scope attributes

Temporal scopes can be:

- Periodic**: controllers, routers, schedulers, streaming processes, ...
- Aperiodic**: periodic 'on average' tasks, i.e. regular but not rigidly timed, ...
- Sporadic / Transient**: user requests, alarms, I/O interaction, ...

Deadlines can be:

- "Hard"**: single failure leads to severe malfunction and/or disaster
- "Firm"**: results are meaningless after the deadline
- "Soft"**: only multiple or permanent failures lead to malfunction
- results are still useful after the deadline

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Summary

Scheduling

- Basic performance scheduling
 - Motivation & Terms
 - Levels of knowledge / assumptions about the task set
 - Evaluation of performance and selection of appropriate methods
- Towards predictable scheduling
 - Motivation & Terms
 - Categories & Examples

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